## In the Claims:

Claims 1-5 (cancelled)

6. (currently amended) A biopsy instrument comprising:

a base assembly comprising a firing mechanism;

a probe assembly detachably mounted to said base, said probe assembly comprising:

a cutter assembly comprising:

a cutter rotatable about its longitudinal axis; and

a piercer assembly comprising:

a piercer having a <u>longitudinal axis</u> and a tissue piercing tip and a side tissue receiving port spaced proximally from the tip, the piercer adapted to be carried distally toward a target by operation of the firing mechanism;

and:

a <u>bevel gear assembly supported by the base and</u> transmission disposed proximally of the piercer, wherein the <u>bevel gear assembly transmission</u> is operable to provide motion of the cutter, wherein the transmission <u>bevel gear assembly</u> receives rotary motion about an axis <u>substantially perpendicular to the longitudinal axis of the piercer reangled with respect to the cutter's longitudinal axis.</u>

7. (canceled).

8-13 (canceled)

14. (canceled).

15. (currently amended) The biopsy instrument of Claim 6 14 wherein the bevel gear assembly transmission comprises at least two gears one gear.

16. (canceled).

- 17. (currently amended) The biopsy instrument of Claim 6-14 wherein biopsy instrument receives a rotary motion input from a an input from the separate source of motion through an clongate member.
- 18. (previously presented) The biopsy instrument of Claim 17 wherein the elongate member comprises a drive cable.
- 19. (currently amended) The biopsy instrument of Claim 6 44 wherein the biopsy instrument receives a first input for translating the cutter from the separate source of motion through a first elongate member, and wherein the biopsy instrument receives a second input for rotating the cutter from the separate source of motion through a second elongate member.
- 20. (currently amended) The biopsy instrument of Claim 6.14-wherein the separate source of motion is disposed in a control unit, and wherein the biopsy instrument receives input from the source of motion through a translation shaft comprising a flexible cable, and from a rotation shaft comprising a flexible cable.